

JACKSON DEAN · RESUME

Skills

### **Blue Dot Impact**

AI SAFETY FUNDAMENTALS

- · Completed a 12-week course focused on AI safety fundamentals, including ethical considerations, regulatory frameworks, and practical applications.
- Learned about the latest advancements in AI safety research and best practices for responsible AI development.

**Kairos Autonomi** Engineer

- Won a US Navy SBIR R&D contract to continue development of a robot capable of autonomously piloting small boats. The project extended
- from initial client meetings to the delivery of several hundred systems.
- Rapidly iterated software, hardware, and procedures for dozens of prototype robotic systems, often going from idea to small-batch production within days.
- Completed a wide variety of projects including robot network communication protocols; PCB design; GitHub administration; field product
- support and service; design and manufacture of injection molded, 3D printed, sheet metal, and CNC-milled parts; supply chain analysis; assembly line optimization.
- Authored a variety of documentation and reports including API specifications, patent applications, user manuals, assembly instructions,
- Experienced working with autonomous ground and air vehicles, especially using Ardupilot control firmware and MAVLink communication protocol.

## Lassonde Make Space

VICE CHAIR

• Hired and managed a team of 15 people who maintain the space and interact with customers.

• Create application specific data processing algorithms to run in resource-constrained systems.

integration of firmware with hardware components and user software.

sive work with I2C, UART, quadrature encoders, DC motors.

• Designed and coordinated workshop events to teach new engineering skills to students.

## Education\_

### **University of Utah**

**B.S. COMPUTER SCIENCE** 

**B.S. MECHANICAL ENGINEERING** 

• Cumulative GPA 3.96

• Relevant Coursework: Natural Language Processing, Data Structures & Algorithms, Mechatronics, Systems Engineering

Technologies Protocol Buffers, MAVLink, ArduPilot

**Programming Languages** C/C++, Python, C#, JavaScript



- May 2020 May 2023

- client progress reports, project proposals, and BOMs.

# Salt Lake City, UT

August 2019 - May 2020

Salt Lake City, UT

December 2022

October 2024 - February 2025

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Salt Lake Citv. UT

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• Designed and ran a series of experiments to increase the accuracy of fiducial detection in new machines from ±0.005 inches to ±0.001

• Design and develop embedded firmware for CNC cutting machines, focusing on performance, reliability, and above all user experience.

· Collaborate with cross-functional teams including hardware engineers, software developers, and product designers to ensure seamless

• Implement low-level device drivers and communication protocols to interface with sensors, motors, and other peripheral devices. Exten-

 Identified numerous long-standing issues with the fiducial detection system that had been impacting customer experience. • Spearheaded the department's adoption of AI code generation and testing tools to increase productivity and reduce errors.

• Develop communication protocols and interfaces between embedded systems and host applications using protobuf.

## Experience \_\_\_\_

**FIRMWARE ENGINEER** 

Cricut

inches.

### South Jordan, UT January 2024 - Present

Sandy, UT